

ROGER MARÍ MOLAS

3D Computer Vision Research Engineer

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EXPERIENCE

Engineering Consultant

Kayrros (April 2019 – Now) 📍 Paris, France

- Provision of consulting services: expertise and software solutions in the field of 3D reconstruction from optical satellite images.

Computer Vision Researcher

Centre Borelli, ENS Paris-Saclay (Oct. 2018 – Now) 📍 Paris, France

- Joined the Image Processing Group of Jean-Michel Morel to work on multi-view 3D reconstruction (classic and neural rendering) and the calibration of camera models adapted to satellite images.

Computer Vision Intern

Mapillary (May 2018 – Aug. 2018) 📍 Barcelona, Spain

- Coded part of a project for camera calibration from a single street-level image and monitored the training of the neural networks employed in it.

Audiovisual Technologies Intern

Eurecat (Jan. 2017 – July 2017) 📍 Barcelona, Spain

- Contributed to the development of a software for 3D reconstruction from multiple images, designed to be used for small objects or faces.

Part-time Instructor

Acadèmia CEUS (Jan. 2015 – July 2016) 📍 Barcelona, Spain

- Gave support lessons on "Waves and Electromagnetism" to groups of 10-25 undergraduate students from Pompeu Fabra University.

EDUCATION

Doctor of Philosophy - PhD in Applied Mathematics

Centre Borelli, ENS Paris-Saclay (2019 - 2022) 📍 Paris, France

- PhD thesis: "Applications of multi-image remote sensing". Started in October 2019 and defended in December 2022. Manuscript available at <https://www.theses.fr/2022UPASM045>.
- Thesis director: Gabriele Facciolo.
- *Paris Region PhD²* doctoral scholarship by Région Île-de-France.

Master's Degree in Computer Vision

Universitat Autònoma de Barcelona (UAB) (2017- 2018) 📍 Barcelona, Spain

- Overall grade (on a scale of 0 to 10): 9.37. Ranked 1st in the class of 2018.
- Master thesis: "Single Image Camera Calibration using Multi-task Neural Networks" (Grade: 9.9/10).
- Graduated with Honors in 7 subjects (48 ECTS credits out of 60).

Bachelor's Degree in Audiovisual Systems Engineering

Universitat Pompeu Fabra (UPF) (2013- 2017) 📍 Barcelona, Spain

- Overall grade (on a scale of 0 to 10): 9.43. Ranked 1st in the class of 2017.
- Bachelor thesis: "Multi-view 3D Reconstruction via Depth Map Fusion for a Smartphone Application" (Grade: 10/10).
- Graduated with Honors in 26 subjects (124 ECTS credits out of 240).

ACHIEVEMENTS

🏆 **Master in Computer Vision 2017 Scholarship for Academic Excellence**
Awarded by Catalunya-La Pedrera Foundation to the student with the best academic record that enrolled the master.

🏆 **Audiovisual Systems Engineering 2017 Extraordinary Award**
Awarded by Pompeu Fabra University to the student ranked 1st in the class of 2017.

PUBLICATIONS

- 📄 López-Antequera, M., Marí, R., Gargallo, P., Kuang, Y., Gonzalez-Jimenez, J., and Haro, G. "Deep Single Image Camera Calibration with Radial Distortion". *CVPR*, 2019.
- 📄 Marí, R., de Franchis, C., Meinhardt-Llopis, E., and Facciolo, G. "To Bundle Adjust or Not: A Comparison of Relative Geolocation Correction Strategies for Satellite Multi-View Stereo". *ICCV Workshops*, 2019.
- 📄 Marí, R., de Franchis, C., Meinhardt-Llopis, E., and Facciolo, G. "Automatic Stockpile Volume Monitoring using Multi-view Stereo from SkySat Imagery". *IGARSS*, 2021.
- 📄 Akiki, R., Marí, R., de Franchis, C., Morel, J.M., and Facciolo, G. "Robust Rational Polynomial Camera Modelling for SAR and Pushbroom Imaging". *IGARSS*, 2021.
- 📄 Marí, R., de Franchis, C., Meinhardt-Llopis, E., Anger, J. and Facciolo, G. "A Generic Bundle Adjustment Methodology for Indirect RPC Model Refinement of Satellite Imagery". *IPOL*, 2021.
- 📄 Marí, R., Ehret, T., Anger, J., de Franchis, C., and Facciolo, G. "L1B+: A Perfect Sensor Localization Model for Simple Satellite Stereo Reconstruction from Push-Frame Image Strips". *ISPRS Annals*, 2022.
- 📄 Marí, R., Facciolo, G. and Ehret, T. "Sat-NeRF: Learning Multi-View Satellite Photogrammetry With Transient Objects and Shadow Modeling Using RPC Cameras". *CVPR Workshops*, 2022.
- 📄 Marí, R., Ehret, T. and Facciolo, G. "Disparity Estimation Networks for Aerial and High-Resolution Satellite Images: A Review". *IPOL*, 2022.

SKILLS

🗨 Languages

- Catalan/Spanish. Native proficiency.
- English. Full professional proficiency.
- French/Italian. Professional proficiency.

⚙ Programming

- Python, Matlab. Advanced level.
- C, C++. Intermediate level.

INTERESTS

Computer Vision Image Processing
3D Reconstruction Remote Sensing
Neural Rendering Camera Calibration